

Phasors

I. The Big Picture (High Level)

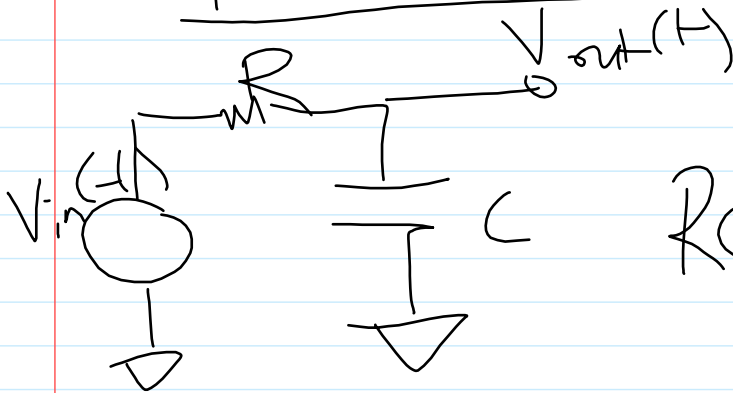
Why have we been learning about diff eq, but jump to complex #s and "phasors"

⇒ Want to make solving diff eq easier

Recall:

$$\frac{dx(t)}{dt} + ax(t) = b(t)$$

← input



$$RC \frac{dV_{out}(t)}{dt} + V_{out}(t) = V_{in}(t)$$

Example

$$X(t) = e^{-\alpha(t-t_0)} \uparrow X_0 + \int_{t_0}^t e^{-\alpha(t-t')} u(t') dt'$$

$\mathcal{L}\{u(t)\} = \frac{1}{s}$

$$X(t_s) = X_0 + \int_{t_0}^t \dots dt$$

$X_h(t)$ $X_p(t)$

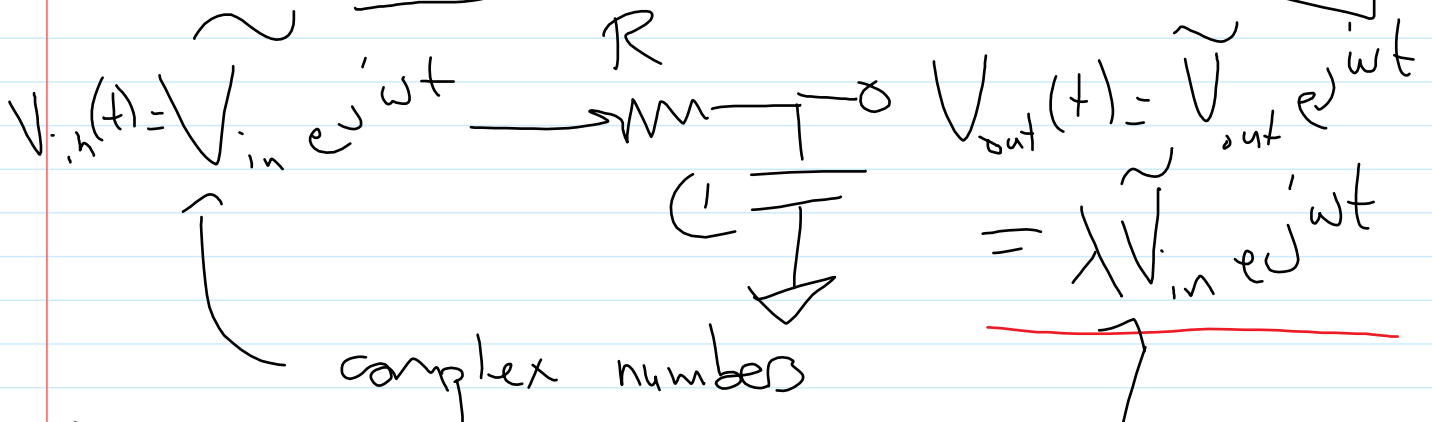
$(t' \text{ is a dummy variable})$

Connection to complex #s;

Plug in $e^{j\omega t}$ (for some reason)

W/ appropriate boundary conditions
 (e.g. $t \rightarrow \infty$ so e^{-at} vanishes)

⇒ We get a steady state response that is just a scaled version of input.



Exploiting eigenfn property of

Exploiting eigen in P.V. of exponentials under differentiation

Suggest we can skip the integral

$$RC \frac{dV_{out}}{dt} + V_{out} = V_{in}$$

$$V_{out}(t) = \tilde{V}_{out} e^{j\omega t}$$

$$V_{in}(t) = \tilde{V}_{in} e^{j\omega t}$$

$$RC(j\omega \tilde{V}_{out} e^{j\omega t}) + \tilde{V}_{out} e^{j\omega t} = \tilde{V}_{in} e^{j\omega t}$$

$$\tilde{V}_{out} (1 + j\omega RC) = \tilde{V}_{in}$$

$$\tilde{V}_{out} = \tilde{V}_{in} = \frac{1}{1 + j\omega RC} \tilde{V}_{in}$$

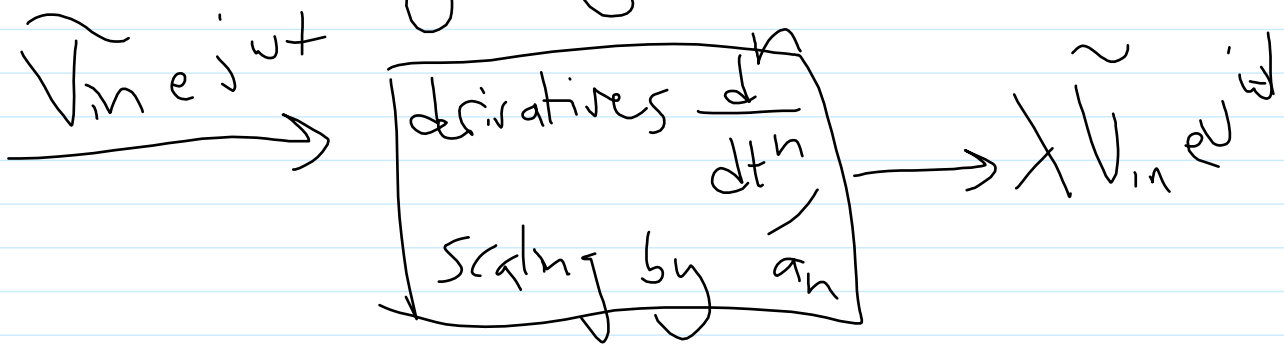
Some Notes

* The gross integral $\int e^{-a(t-t')} u(t') dt'$

- works for any input, not just $e^{i\omega t}$
- ★ But integrals are hard
- ★ What if we wanted to look at a more complicated diff eq (e.g. more complex circuit)

→ take hint of eigenfn property of $e^{i\omega t}$

Expect method of plug in $\tilde{V}_{in} e^{i\omega t}$, get out $\tilde{V}_{out} e^{i\omega t}$ to work for any diff eq only containing derivatives and multiplying by constants



But why $e^{j\omega t}$???

The (short) answer:

we care about sinusoidal inputs
(eg. 60 Hz AC from wall)

$$V_m \cos(\omega t + \varphi) = \operatorname{Re} \left\{ \tilde{V}_m e^{j\omega t} \right\}$$

\tilde{V}_m is called the **phasor** of
the signal $V_m(t)$

$$\tilde{V}_m = V_m e^{j\varphi} \leftarrow \begin{array}{l} \text{phase of} \\ \text{the signal} \end{array}$$

↑
amplitude of signal

$$\begin{aligned} V_m \cos(\omega t + \varphi) &= V_m e^{j(\omega t + \varphi)} + V_m e^{-j(\omega t + \varphi)} \\ &= \underbrace{(V_m e^{j\varphi})}_{\uparrow} e^{j\omega t} + \underbrace{(V_m e^{-j\varphi})}_{\uparrow} e^{-j\omega t} \end{aligned}$$

$$= \frac{(V_{in} e^{j\omega t}) e^{-j\omega t} + (V_{in} e^{-j\omega t}) e^{j\omega t}}{2}$$

$$= \frac{\tilde{V}_{in} e^{j\omega t} + \tilde{V}_{in} e^{-j\omega t}}{2}$$

Clearly, plugging in $\tilde{V}_{in} e^{j\omega t}$ is easier than $V_{in} \cos(\omega t + \phi)$

EX:

$$RC \frac{dV_{out}(t)}{dt} + V_{out}(t) = V_{in} \cos(\omega t + \phi)$$

same equation

$$RC \frac{d}{dt} \operatorname{Re}\{\tilde{V}_{out} e^{j\omega t}\} + \operatorname{Re}\{\tilde{V}_{out} e^{j\omega t}\} = \operatorname{Re}\{\tilde{V}_{in} e^{j\omega t}\} \quad (1)$$

It can be shown (using linearity mainly) that solving the

equation for complex exp.

$$(2) \quad RC \frac{d}{dt} (\tilde{V}_{out} e^{j\omega t}) + \tilde{V}_{out} e^{j\omega t} = \tilde{V}_{in} e^{j\omega t}$$

also solves the eqn w/ cosine

(Solving simpler eqn 2 \rightarrow solves 1)


III. The Mechanics

(what you need to know
definitely)

Motivation for phasor analysis procedure
* even setting up the diff eq can be hard

* would like an even simpler procedure where we skip the diff eq \leftarrow what???

Look at R, L, C:



$$I_c(t) = C \frac{dV_c(t)}{dt}$$

Put in $\tilde{V}_c e^{j\omega t}$
for $\tilde{I}_c e^{j\omega t}$ solve

Same as if we had put in
 $V_c(t) = \Re \{ \tilde{V}_c e^{j\omega t} \} = V_c \cos(\omega t + \phi)$

$$\cancel{\tilde{I}_c e^{j\omega t}} = C \frac{d}{dt} (\tilde{V}_c e^{j\omega t})$$

$$= C j\omega \tilde{V}_c e^{j\omega t}$$

$$\tilde{V}_c = \frac{1}{j\omega C} \tilde{I}_c = Z_C \tilde{I}_c$$

Similarly, inductors:

$$V_{in} = \tilde{V}_{in} e^{j\omega t}$$

$$V_L = L \frac{dI_L}{dt}$$

$$\tilde{V} e^{j\omega t} = L \frac{d}{dt} \tilde{I}_L e^{j\omega t}$$

$$\boxed{\tilde{V}_L = j\omega L \tilde{I}_L = Z_L \tilde{I}_L}$$

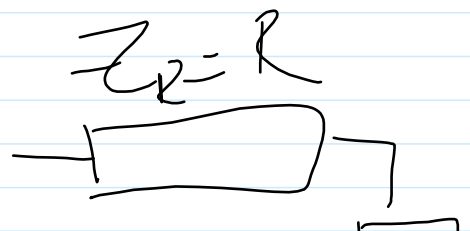
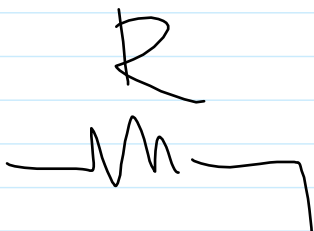
Each ckt element contributes its own diff eq of sorts to the final diff eq (for sinusoidal inputs)

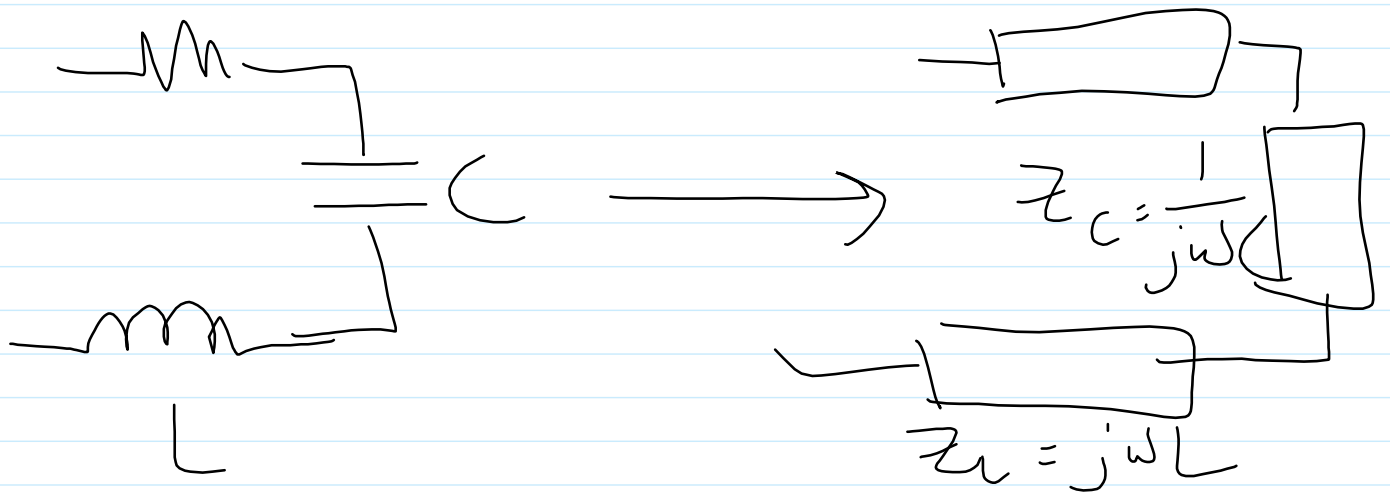
→ Then setting up the full diff eq (e.g. RC ckt from earlier) amounts to working with:

* "phasor $\tilde{I}-\tilde{V}$ " $\Rightarrow \tilde{V} = Z \tilde{I}$

* "complex valued resistors"

\Rightarrow impedances





From here; use ckt solving techniques from 16A!

~~***~~ 5-step method for ~~***~~ phasor analysis

① Cosine reference; convert all signals into cosines

$$V_o \cos(\omega t + \phi) = \text{Re} \left\{ \underbrace{V_o e^{j\phi}}_{V_o \text{ phasor}} e^{j\omega t} \right\}$$

② Transform ckt to phasor domain;

$$v(t) \longrightarrow \tilde{V} = V_0 e^{j\phi_v}$$

$$i(t) \longrightarrow \tilde{I} = I_0 e^{j\phi_i}$$

$$R, L, C \longrightarrow Z_R = R$$

$$Z_L = j\omega L$$

$$Z_C = \frac{1}{j\omega C}$$

$$\frac{1}{j} = -j$$

$$\frac{1}{j} \times \frac{j}{j} = \frac{j}{j^2} = -j$$

$$= \frac{-j}{\omega C}$$

③ Use KCL, KVL in phasor domain.

④ Solve for unknowns.

⑤ Transform back to time domain.

$$V_0 e^{j\phi} \longrightarrow V_0 \cos(\omega t + \phi)$$

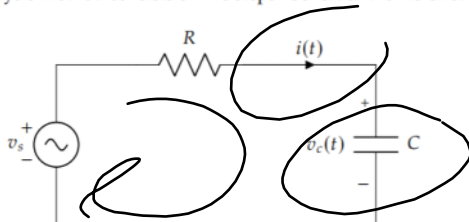
2 Phasor Analysis

Any sinusoidal time-varying function $x(t)$, representing a voltage or a current, can be expressed in the form

$$x(t) = \Re\{Xe^{j\omega t}\}, \tag{1}$$

where X is a time-independent function called the phasor counterpart of $x(t)$. Thus, $x(t)$ is defined in the time domain, while its counterpart X is defined in the phasor domain.

The phasor analysis method consists of five steps. Consider the RC circuit below.



The voltage source is given by

$$v_s(t) = 12 \sin\left(\omega t - \frac{\pi}{4}\right), \tag{2}$$

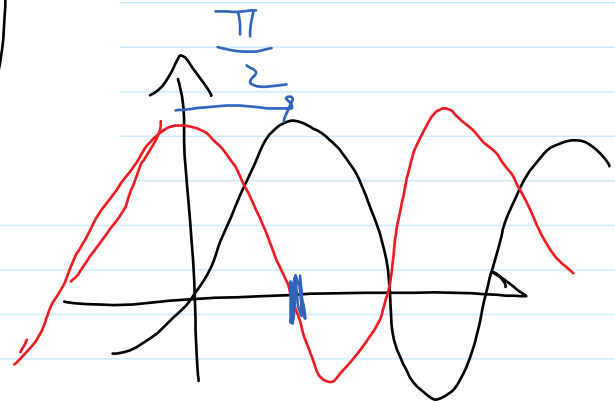
with $\omega = 1 \times 10^3 \frac{\text{rad}}{\text{s}}$, $R = \sqrt{3} \text{k}\Omega$, and $C = 1 \mu\text{F}$.

Our goal is to obtain a solution for $i(t)$ with the sinusoidal voltage source $v_s(t)$.

a) Step 1: Adopt cosine references

All voltages and currents with known sinusoidal functions should be expressed in the standard cosine format. Convert $v_s(t)$ into a cosine and write down its phasor representation \tilde{V}_s .

$$v_s(t) = 12 \sin\left(\omega t - \frac{\pi}{4}\right)$$



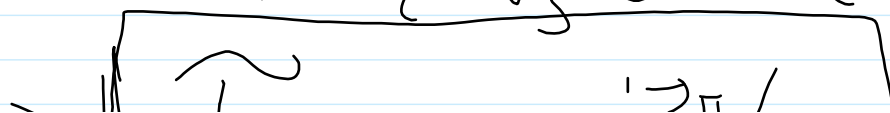
convert cos \rightarrow sine

Subtract $\frac{\pi}{2}$ ← shift by $\frac{\pi}{2}$ "forward"

$$v_s(t) = 12 \cos\left(\omega t - \frac{\pi}{4} - \frac{\pi}{2}\right)$$

$$= 12 \cos\left(\omega t - \frac{3\pi}{4}\right)$$

$$= \Re\left\{ V_s e^{j\phi_s} e^{j\omega t} \right\}$$



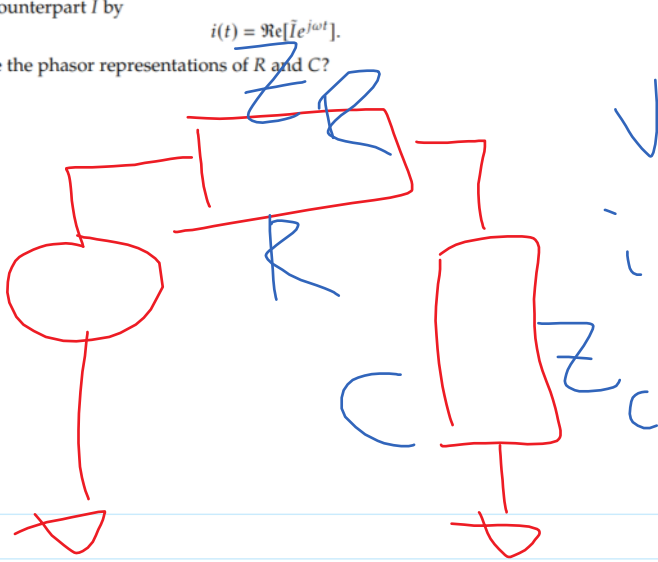
$$\Rightarrow \boxed{V_s = 12e^{-j3\pi/4}}$$

b) Step 2: Transform circuits to phasor domain

The voltage source is represented by its phasor \tilde{V}_s . The current $i(t)$ is related to its phasor counterpart \tilde{I} by

$$i(t) = \Re[\tilde{I}e^{j\omega t}]$$

What are the phasor representations of R and C?



$$V_s(t) \rightarrow \tilde{V}_s$$

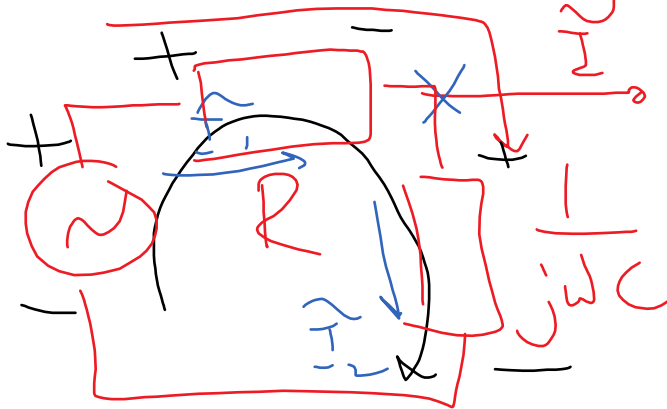
$$i(t) \rightarrow \tilde{I}$$

$$Z_R = R$$

$$Z_C = \frac{1}{j\omega C}$$

c) Step 3: Cast KCL and/or KVL equations in phasor domain

Use Kirchhoff's laws to write down a loop equation that relates all phasors in Step 2.



KCL:

$$\vec{I}_1 = \vec{I}_2 = \vec{I}$$

$$-\vec{V}_s + \vec{V}_R + \vec{V}_C = 0$$

$$\vec{V}_s = \vec{I} (Z_R + Z_C)$$

$$\vec{V}_s = 12 e^{j \frac{311}{4}} = \vec{I} \left(R + \frac{1}{j\omega C} \right)$$

$$\Rightarrow \vec{I} = \frac{\vec{V}_s}{R + \frac{1}{j\omega C}}$$

$$\vec{I} = \frac{j\omega C \vec{V}_s}{1 + j\omega RC}$$

$$\vec{V}_C = Z_C \vec{I} = \frac{1}{j\omega C} \times \frac{j\omega C \vec{V}_s}{1 + j\omega RC}$$

$$\Rightarrow \vec{V}_C = \frac{\vec{V}_s}{1 + j\omega RC}$$

← Try to check

$$\Rightarrow \left[\tilde{V}_c = \frac{V_s}{1 + j\omega RC} \right]$$

← voltage divider, see if it matches! (it should)

d) Step 4: Solve for unknown variables

Solve the equation you derived in Step 3 for \tilde{I} and \tilde{V}_c . What are the polar forms of \tilde{I} ($Ae^{j\theta}$, where A is a positive real number) and \tilde{V}_c ?

$$\tilde{I} = \frac{V_s j\omega C}{1 + j\omega RC} = j 12 e^{-j\frac{3\pi}{4}} \frac{(10^3 \frac{\text{rad}}{\text{s}}) \times (1 \mu\text{F})}{1 + j (10^3) (1 \mu\text{F}) (\sqrt{3} \text{ k}\Omega)}$$

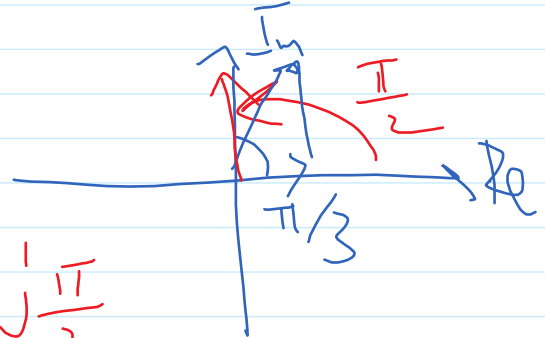
$$= \frac{12 j e^{-j\frac{3\pi}{4}} \times 10^{-3} \text{ A}}{1 + j\sqrt{3}}$$

(polar)

$$= \frac{12 j e^{-j\frac{3\pi}{4}} \text{ mA}}{\sqrt{1^2 + \sqrt{3}^2} e^{j(\arctan(\sqrt{3}, 1))}}$$

$$= \frac{12 j e^{-j\frac{3\pi}{4}} \text{ mA}}{2 e^{j\pi/3}}$$

$$= \frac{12 e^{-j\frac{3\pi}{4}} e^{j\frac{\pi}{2}}}{2 e^{j\pi/3}} = \frac{6 e^{-j\frac{\pi}{4}}}{e^{j\pi/3}} = -\frac{\pi}{4} - \frac{\pi}{3} = -\frac{7\pi}{12}$$



$$\tilde{I} = \dots - \frac{7\pi}{12}$$

$$\therefore \underline{\underline{I}} = 6e^{-j\frac{7\pi}{12}}$$

$$\underline{\underline{V}}_c = \frac{\underline{\underline{V}}_s}{1 + j\omega RC} = \frac{12e^{-j\frac{3\pi}{4}}}{1 + j\sqrt{3}} = \frac{12e^{-j\frac{3\pi}{4}}}{2e^{j\frac{\pi}{3}}} = 6e^{-j\frac{13\pi}{12}}$$

$$-\frac{3\pi}{4} - \frac{\pi}{3} = -\frac{13\pi}{12}$$

e) Step 5: Transform solutions back to time domain

To return to time domain, we apply the fundamental relation between a sinusoidal function and its phasor counterpart. What is $i(t)$ and $v_c(t)$? What is the phase difference between $i(t)$ and $v_c(t)$?

$$i(t) = \operatorname{Re} \left\{ \underline{\underline{I}} e^{j\omega t} \right\}$$

$$= \frac{\underline{\underline{I}} e^{j\omega t} + \overline{\underline{\underline{I}} e^{j\omega t}}}{2} \quad \text{mA}$$

$$= \frac{6e^{-j\frac{7\pi}{12}} e^{j\omega t} + 6e^{j\frac{7\pi}{12}} e^{j\omega t}}{2} \quad \text{mA}$$

$$= \frac{12 \cos\left(\omega t - \frac{7\pi}{12}\right)}{2} \quad \text{mA}$$

$$\underline{\underline{i(t) = 6 \cos\left(\omega t - \frac{7\pi}{12}\right) \text{ mA}}}$$

$$V_0 \cos(\omega t + \varphi) = \Re \{ V_0 e^{j\varphi} e^{j\omega t} \}$$

$$\vec{V}_c = 6 e^{-j \frac{13\pi}{12}}$$

$$\Rightarrow \boxed{V_c(t) = 6 \cos\left(\omega t - \frac{13\pi}{12}\right) \text{ V}}$$